

3-Part Architectural Specifications

Electric Door Operator

Model: OHJ

Part 1 General

1.01 Description

A. Work Included: supply and installation of a heavy-duty V-belt drive Jackshaft type electric door operator with a self-engaging hoist, manual egress release and mechanical brake, of size and capacity recommended by door manufacturer, as specified; as well as the necessary driving hardware and control accessories necessary for proper operation.

B. Mounting: to be wall mounted (or Vertical Front of Hood mounted) (or Horizontal Top of Hood mounted). On the right (or on the left) of the door. Hoist position on the right of operator (or on the left of operator).

1.02 Related Work

A. Door preparation, miscellaneous or structural metal work, field electrical wiring, wires, disconnect switches, fuses and conduit are in the scope of work of other sections or trades.

1.03 Submittals

A. Submit manufacturer's product data and installation instructions for each type of operator. Include both published data and any specific data prepared for this project.

1.04 Delivery, Storage and Handling

A. Product shall be delivered to the project site in manufacturer's original packaging.

B. Product shall be handled and stored to prevent damage to materials, finishes and operating mechanisms.

1.05 Warranty

A. Operator shall be warranted to be free from defects in material and workmanship for a period of 2 years.

Part 2 Product

2.01 Manufacturer

A. Acceptable Product: Operator model Opera-HJ as manufactured by Manaras-Opera, part of the Canimex Group.

2.02 Operator

A. Motor: to be rated ___Hp, ___ Volts, ___Phase60Hz high starting torque, continuous-duty single phase capacitor start or 3 phase motor, open drip proof, protected against overload by a built-in thermal protection with automatic reset (3 phase motors) or a current sensing device with manual reset (1 phase motors). Also available with 50Hz 220V 1 phase and 380V 3 phase motor. Motor shall be separate from reduction mechanism for ease of maintenance.

B. Reduction: first step in reduction to be 5L V-belt drive, additional steps by chain and sprockets providing mechanical braking to hold the door in any position and giving an output shaft speed of 41 rpm. Input steel shaft to be a minimum of 5/8" (18.875mm) in diameter and supported by precision ball bearings. Output steel shaft to be a minimum of 1" (25.4mm) in diameter with 1/4" keyway and supported by ball bearings.

C. Drive: door shaft to be driven by a #50 roller chain and 50B12 sprocket combination to provide door travel of 6" (152.4mm) to 12" (304.8mm) per second.



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D. Clutch: to be friction type, positioned on input shaft, adjustable from outside.

E. Brake: to be a mechanical brake.

F. Manual Operation: to be by a Hoist-a-matic® self-engaging hoist (not requiring a floor level engagement device to operate) for manual chain operation, as well as a manual egress release. An electrical interlock automatically disconnects power to the motor operator when the chain hoist or egress are engaged.

G. Electrical Enclosure: all electrical components to be in a NEMA 1 enclosure. The enclosure to be hinged with stable opened position for easy access to mechanical components and mounting holes.

H. Limit Switches: to be rotary-type with oil-impregnated steel cams, commercial grade switches. Systems to be enclosed in electrical control box, and limit shaft to be supported in frame by self-lubricating bronze bushing. System to be provided with Accu-cam® precise and quick one-handed adjustment feature. Limit switches to remain in time when there is a manual operation or after the motor as been removed. Designed to prevent any lever breakage when limits have been exceeded during manual operation.

I. Corrosion Protection: Frame and control enclosure to be protected by baked on, long lasting enamel finish. All shafts to be protected by yellow chromate coating.

J. Motor Control: to be a 24VDC relaying and 5VDC logic circuit with a 40VA class II transformer, non-volatile memory, fused protected on output, centrifugal switch relay, programmable micro-processor. Includes 1.5s delay on reverse, door lock sensor to prevent damage to the door when the lock is engaged, reverse wiring detection, programmable advance close system, programmable maximum run timer, mid-stop, timer to close, test buttons. Operating mode selection to be possible on site during or after installation. Terminal strip to allow connection of 3-button stations (one supplied with the operator), sensing edges, photo cells, one push-button radio control (external strip), ceiling pull and key switches, loop detectors, external interlocks. 2A fuse protected 24VAC output is available for accessory power supply. Operating mode D1 and door lock sensor standard.

K. Operating mode: to be D1 (or C2 or B2 or E2, see appendix for description).

Note to architects:

Motorized doors can cause serious injuries or death. Manaras-Opera strongly recommends the use of entrapment protection systems, especially in case of momentary contact to close as in B2, T or TS operating modes.

L. Control Accessories to be supplied: 3 push-button stations, open close key switch, one button radio control, electric sensing edge, pneumatic sensing edge, through beam photo cell.

M. Standards: operator to be certified UL 325 or CSA22.2/247 by a National Recognized Testing Laboratory such as UL or CSA.

Part 3 Execution

3.01 Installation

A. Installation: to be in accordance with Manaras-Opera instructions and in compliance with federal, state or local regulations.

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Appendix: WIRING TYPE Descriptions

C2 Wiring (0): Factory preset as per UL325. Momentary contact to open/stop, constant pressure to close with a 3 push-button station. Activation of entrapment detection devices will reverse the door during closing. Auxiliary devices function as an open control and to reverse the door during closing.

B2 Wiring (1): Momentary contact to open/close/stop with a 3 push-button station. Activation of entrapment detection devices will reverse the door during closing. Auxiliary devices function as open/close control and reverse the door during closing.

D1 Wiring (2): Constant pressure to open/close. Activation of entrapment detection devices will stop the door during closing.

E2 Wiring (3): Momentary contact to open, constant pressure to close. Release of close button activates the door upwards. Activation of entrapment detection devices will reverse door motion to its fully open position.

T Wiring (4): Momentary contact to open/close/stop. The door will close when the timer is expired. If the entrapment detection devices reverse upon activation, the TTC will be deactivated. When the door is at its open limit, if the entrapment detection devices are activated, or if the chain hoist is engaged, or if the stop button is pushed before time-out, it will deactivate the TTC. The TTC will get refreshed if there is a power outage, or if the radio control device is activated, or if the open button is activated. The TTC resumes its normal operation once the close cycle is completed.

TS Wiring (5): Momentary contact to open/close/stop. The door will close when the timer is expired. If the entrapment detection devices reverse upon activation, it will refresh the TTC. When the door is at its open limit, the TTC will also get refreshed if there is a power outage, or if the chain hoist is engaged, or if the radio control device is activated, or if the open button is activated, or if the stop button is pushed before time-out.